

b. Design simplified combinational logic circuit to compute the hash function by Karnaugh mapping.

3. Computer controlled robot arms are used in industry to manufacture precision parts of many products. Error free and precise positioning of the gripper (robot hand) requires optical encoders with gray code output at the joints of the robot arm. Code convertors convert gray code signals from encoders to pure binary signals before they are processed by the computer.
- a. Construct the truth table of 3 bit gray code inputs $X_2X_1X_0$ and corresponding pure binary outputs $Y_2Y_1Y_0$ for a gray to binary code convertor,
- b. Design simplified combinational logic circuit to convert 3 bit gray code to pure binary code by Karnaugh mapping,
- c. Draw the schematic diagram of a convertor to read angular position (rotation) of a robot arm joint with at least 1 degree angular resolution.